





#### Application Package for Facemask Making Machines iQ Monozukuri FACEMASK

MITSUBISHI ELECTRIC ASIA PTE LTD





#### What is iQ Monozukuri?



A package providing **optimal solutions** for each process, application, and machine to achieve **higher productivity and quality**. It also gives ideas for **easier system configuration**. iQ Monozukuri lays the foundation for "**e-F@ctory**" implementation.





## Mask Making Machine & Supported FBs

- Constant control of the unwinding tension of sheets is performed easily.
- Cam operation is automatically generated as electronic cams.







#### System Configuration

| Sorios | Function         |            | Supported notwork | Simple Motion | Convo amplifiar |  |
|--------|------------------|------------|-------------------|---------------|-----------------|--|
| senes  | Unwinder control | Cutter cam | Supported network | module        | Servo ampimer   |  |
| io p   | 0                | 0          | CC-LinklE Field   | RD77GF_       | MR-J4GF         |  |
|        |                  | 0          |                   | RD77MS_       | MR-I/I- B       |  |
| iO-F   | _                | 0          | SSCNET III/H      | FX5-40SSC-S   | MR-JE- B        |  |
|        |                  |            |                   | FX5-80SSC-S   |                 |  |
|        |                  |            |                   |               |                 |  |





## **FACEMASK Library**

#### List of FBs for MELSEC iQ-R

| Item                            | Name                            | Description  |  |
|---------------------------------|---------------------------------|--|--|
| Cam auto-                       | STD_MakeRotaryCutterCam         | Cam auto-generation for rotary cutter                              |  |
| generation                      | STD_MakeFlyingShearCam          | Cam auto-generation for flying shear                               |  |
| synchronization control         | CtrlOutputAxisSync              | Output axis synchronization control                                |  |
| Tension<br>control              | CNV_WinderTensionSensorlessCtrl | Tension sensorless torque<br>control                               |  |
| Roll<br>diameter<br>calculation | CNV_DiaCalcThickness            | Roll diameter calculation<br>(web thickness integration<br>method) |  |
| Filters                         | CNV_EdgePositionCtrl            | Edge position control  |  |
| Tuning<br>function              | PIDControl                      | PID control  |  |
| Filters                         | STD_Limiter                     | Limiter  |  |





## FACEMASK Library

#### List of FBs for MELSEC iQ-F

| Item                    | Name                    | Description                           |  |
|-------------------------|-------------------------|---------------------------------------|--|
| Cam auto-               | STD_MakeRotaryCutterCam | Cam auto-generation for rotary cutter |  |
| generation              | STD_MakeFlyingShearCam  | Cam auto-generation for flying shear  |  |
| Synchronization control | CtrlOutputAxisSync      | Output axis synchronization control   |  |





#### Introduction to Program

Simply drag & drop the FBs into a work sheet of GX Woks3, making programming easy and intuitive.







#### Cam Auto-Generation for Rotary Cutter



Only parameter settings of sheet length and sheet synchronization width are required. A cam for driving a rotary cutter is automatically generated.





#### **Cam Auto-Generation for Rotary Cutter**







#### **Cam Auto-Generation for Flying Shear**



Only parameter settings of synchronization starting/ending point is required. A cam for a flying shear is automatically generated.





#### **Cam Auto-Generation for Flying Shear**



- Execution status
- Normal/
- error completion
- Error code



Cam control to the output axis with the advanced synchronous control



- Cam waveforms making smooth start and stop
- The FB does all the complex calculations.







In unwinder control, coefficient of taper is kept at 1.

The command torque is calculated from the unwinding roll diameter, and outputted to the nplifier.





#### **Edge-Position Control**

To achieve the edge sensor target value, the position correction value determined by the PID control is output as command velocity.



Position correction of the unwinding sheet

# MITSUBISHI ELECTRIC Changes for the Better